/	DISCIPLINE ELECTRICAL	510		
	ENGG SUB- EC-II		SEMESTER FROM 01.10.2021 TO 28.02.2022 NO OF WEEK – 16 WEEKS	
		ALLOTED- 4 CLASS DAY	THEORY	STATUS
-	VEEK	1 st day 2 nd day 3 rd day 4 th day	 ALTERNATOR: 1.1. Types of alternator and their constructional features. 1.2. Basic working principle of alternator and the relation between speed and 	
2 ND	WEEK	1 ST day 2 nd day 3 rd day 4 th day	 frequency. 1.3. Terminology in armature winding and expressions for winding factors (Pitch factor, Distribution factor). 1.4. Explain harmonics, its causes and impact on winding factor. 1.5. E.M.F equation of alternator. (Solve numerical problems). 1.6. Explain Armature reaction and its effect on emf at different power factor 	Constate
3 RD W 4 TH WE	ЕК 1	1 ST day 2 nd day 3 rd day 4 th day	of load. 1.7. The vector diagram of loaded alternator. (Solve numerical problems) 1.8. Testing of alternator (Solve numerical problems) 1.8.1. Open circuit test. 1.8.2. Short circuit test. 1.9. Determination of voltage regulation of Alternator by direct loading and synchronous impedance method. (Solve numerical problems) 1.10. Parallel operation of alternator using synchro-scope and dark & bright lamp method. 1.11. Explain distribution of load by parallel	
5 [™] WEEK		rd day th day	connected alternators.	Constrate

	10		
	1 st day	Availati	
	<"day	excitation.	
	3" day	2.5. Effect of varying excitation with constant load	
	4 th day	constant load.	
		2.6. Power angle characteristics of cylindrical rates material	
		2.7. Explain effect of excitation on Armature current and nower factor	
	1 st day		
	2 nd day	2.8. Hunting in Synchronous Motor. 2.9. Function of Damper Bars in	
6 [™] WEEK	3 rd day	Synchronous motor and an	
6" WEEK	4 th day	synchronous motor and generator. 2.10. Describe method of starting of	
			Complete
		2.11. State application of synchronous	0,
		3. THREE PHASE INDUCTION MOTOR:	
		3.1. Production of rotating magnetic field.	
	1 ^{s⊤} day	3.2. Constructional feature of Squirrel cage	
	2 nd day	and Slip ring induction motors.	
7 [™] WEEK	3 rd day	3.3. Working principles of operation of 3-	
	4 th day	phase induction motor.	
		3.4. Define slip speed, slip and establish	complete
	Í [the relation of slip with rotor quantities	Coloris
	Í l	3.5. Derive expression for torque during	
	Í I	starting and running conditions and	
		derive conditions for maximum	
		torque. (solve numerical problems)	
		3.6. Torque-slip characteristics.	
		3.7. Derive relation between full load	
	1 st day	torque and starting torque etc. (solve	
8 TH WEEK	2 nd day	numerical problems)	
	3 rd day	3.8. Establish the relations between Rotor	i I
	4 th day	Copper loss, Rotor output and Gross	
		Torque and relationship of slip with	
		rotor copper loss. (solve numerical	
		problems)	
		3.9. Methods of starting and different	
		types of starters used for three phase	Conflict
		Induction motor.	Calup .
		3.10. Explain speed control by Voltage	
		Control, Rotor resistance control,	
		Pole changing, frequency control	
	1 ^{s⊤} day	methods.	
9 [™] WEEK	2 nd day	3.11. Plugging as applicable to three phase	
	3 rd day	3.11. Plugging as applicable to three provident	
	4 th day	3.12. Describe different types of motor	
	4" uay	3.12. Describe amerent upos of	
		enclosures.	
		3.13. Explain principle of Induction Generator	
		and state its applications.	

10 TH WEE	1 st day 2 nd day 5K 3 rd day 4 th day	 4. SINGLE PHASE INDUCTION MOTOR: 4.1. Explain Ferrari's principle. 4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase induction motor. 4.3 Explain Working principle. 	
11 [™] WEEK	1 ^{s⊤} day 2 nd day 3 rd day 4 th day	 4.3. Explain Working principle, Torque speed characteristics, performance characteristics and application of following single phase motors. 4.3.1. Split phase motor. 4.3.2. Capacitor Start motor. 4.3.3. Capacitor start, capacitor run motor. 4.3.4. Permanent capacitor type motor. 4.3.5. Shaded pole motor. 4.4. Explain the method to change the direction of rotation of above motors. 	Complete
12 [™] WEEK	1 ^{s⊤} day 2 nd day 3 rd day 4 th day	 COMMUTATOR MOTORS: 5.1. Construction, working principle, running characteristic and application of single phase series motor. 5.2. Construction, working principle and application of Universal motors. 	Dupletie
13 [™] WEEK	1 ^{s⊤} day 2 nd day	5.3. Working principle of Repulsion start Motor, Repulsion start Induction run motor, Repulsion Induction motor.	Cane
14 TH WEEK	3 rd day 4 th day 1 ST day 2 nd day 3 rd day 4 th day	 SPECIAL ELECTRICAL MACHINE: Principle of Stepper motor. Classification of Stepper motor. Principle of variable reluctant stepper motor. Principle of Permanent magnet stepper motor. Principle of hybrid stepper motor. Applications of Stepper motor. 	Oreflekt
15 TH WEEK	1 st day 2 nd day 3 rd day 4 th day	 THREE PHASE TRANSFORMERS: 7.1. Explain Grouping of winding, Advantages. 7.2. Explain parallel operation of the three phase transformers. 7.3. Explain tap changer (On/Off load tap changing) 7.4. Maintenance Schedule of Power Transformers. 	Concluste

16TH WEEK

1st day 2nd day

REVISION FOR EXAM

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Subject :-	No of Days/Per	No Of Weeks : - 27	
Circuit	week Class Allotted :- 04		STATUS
Theory(In2)	CLASS		
WEEK	DAY	MAGNETIC CIRCUITS :- Introduction	~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~~
in the second second	1 st	MAGNETIC CIRCUITS :- Infroduction Magnetizing force, Intensity, MMF, flux and their relations	2ª
1 ST	2 nd	Permeability, reluctance and permeance	- OT
10,	3 rd	Permeability, reluciance and permeability, reluciance and Magnetic Circuits	ره
	4 th	Permeability, reluctance and Magnetic Circuits	
A in the second	1 st		e e e e e e e e e e e e e e e e e e e
-	2 nd	B-H Curve Series & parallel magnetic circuit.	J.
2 ND	3 rd	Hysteresis loop COUPLED CIRCUITS :- Self Inductance and Mutual	a a
	4.45	COUPLED CIRCUITS :- Seit inductance	CO
	4 th	Inductance Conductively coupled circuit and mutual impedance	J.
	1 st .	Conductively coupled circuit and material	2ª
3 RD	2 nd	Dot convention; Coefficient of coupling Series and parallel connection of coupled inductors.	×
	3 rd	a in the second problems	معن ا معن
	4 th	Solve numerical problems CIRCUIT ELEMENTS AND ANALYSIS :-Active, Passive,	1 1
	1.st	Lusiateral & bilateral Linear & Non linear elements.	
		Active, Passive, Unilateral & bilateral, Linear & Non linear	2
	2 nd	alamanta	5
	- Bender -	Mesh Analysis, Mesh Equations by inspection, Super mesh	2
4 TH	3 rd	Analysis	E
14 - X		Nodal Analysis, Nodal Equations by inspection, Super node	2
	4 th	Analysis.	
	1 st	Source Transformation Technique.	+
5 TH	2 nd	Solve numerical problems (With Independent Sources Only).	S.
	3 rd	NETWORK THEOREMS :- Introduction	<u>a</u>
	3 ra 4 th	Star to delta transformation	Contraction of the second seco
	4 ui 1 st	Delta to star transformation	
	2 nd	Super position Theorem	
6 ТН	3 rd	Thevenin's Theorem	A A A A A A A A A A A A A A A A A A A
	4 th	Norton's Theorem	(°
	1 st	Maximum power Transfer Theorem.	
7 TH	2 nd	Solve numerical problems (With Independent Sources Only)	
	1. J. M. 1.	AC CIRCUIT AND RESONANCE :- INTRODUCTION	e a la la la
	4 th	A.C. through R-L, R-C & R-L-C Circuit	completed
		Solution of problems of A.C. through R-L, R-C & R-L-C series	complete
	1 st	Circuit by complex algebra method.	completed
8 TH	2 nd	Solution of problems of A.C. through R-L, R-C & R-L-C parallel &	
		Composite Circuits	complete
	3 rd	Power factor & power triangle.	complete
	4 th	Deduce expression for active, reactive, apparent power.	complete
9 ТН	1 51	Derive the resonant frequency of series resonance	comp leter
	3 rd	Derive the resonant frequency parallel resonance circuit	completed
	4 th	Define Bandwidth, Selectivity & Q-factor in series circuit.	completed
	1 st	Solve numerical problems	completed
10 TH	C. Transferrer	ONLINE TEST	completed
	2 nd	POLYPHASE CIRCUIT:- Concept of poly-phase system and phase sequence	
	3 rd	Relation between phase and line quantities in star & delta	completed
		Som ection	1.41
	4 th	Power equation in 3-phase balanced circuit	completed
		Solve numerical problems	completer
L	2 nd	Measurement of 3-phase power by two wattmeter method.	completed
		inethold.	Comin la tod

11 TH	3 rd	Solve numerical problems.	completed
11.04	4 th	TRANSIENTS:- INTRODUCTION	comple for
	1 st	Steady state Response.	completer
12 TH	2 nd	transient state response.	completed
	3 rd	Response to R-L, R-C under DC condition	completer
	4 th	RLC circuit under DC condition.	completed
	1 st	Solve numerical problems	completer
13 TH	2 nd	TWO-PORT NETWORK :- INTRODUCTION	completes
	3 rd	Open circuit impedance (z) parameters	completed
	4 th	Short circuit admittance (y) parameters	completed
	1 st	Transmission (ABCD) parameters	complates
14 TH	2 nd	Hybrid (h) parameters.	completed
	3 rd	Inter relationships of different parameters.	completed
	4 th	T and π representation.	completed
	1 st	Solve numerical problems	completed
15 TH	2 nd	FILTERS :- Define filter	comp loted
	3 rd	Classification of pass Band, stop Band and cut-off frequency.	completed
	4 th :	Classification of filters.	completed
	1 st	Constant – K low pass filter & Constant – K high pass filter.	completed
	2 nd	Constant – K Band pass filter & Constant – K Band elimination filter.	completed
16 TH	3 rd	Solve Numerical problems	
20 111	4 th	ONLINE TEST	completes
	1 st	UNLINE I EST	completer
17 TH	2 nd		
	3 rd	REVISION AND CLASS TEST	completed
	4 th		
18 TH	1 st 2 nd		
	3 rd	REVISION AND CLASS TEST	completed
	4 th		
10.71	1 st		
19 TH	2 nd 3 rd	REVISION AND CLASS TEST	(could be)
	4 th		completed
	1 st		
20 TH	2 nd	REVISION AND CLASS TEST	
	3 rd		completed
	4 th 1 st		
	2 nd		
21 TH	3 rd	REVISION AND CLASS TEST	completed
<u></u>	4 th		
22 TH	1 st		
	2 nd 3 rd	REVISION AND CLASS TEST	Comple b-1
	4 th		Completed
1	1 st		
23 RD	2 nd		con (b)
	3 rd	REVISION AND CLASS TEST	completed
1	4 th		
	1 st 2 nd		
24 TH	3 rd	REVISION AND CLASS TEST	completed
	4 th		
	1 st		
25 TH	2 nd	REVISION AND CLASS TEST	
•	3 rd 4 th		completed
1992.00	4 tri		
26 TH	2 nd		
	3 rd	REVISION AND CLASS TEST	completed
-	4 th		
	1 st		
27 TH	2 nd	REVISION AND CLASS TEST	complete
1	3 rd 4 th		and the
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