

(1) What is the function of armature winding in a dc generator? Distinguish betwⁿ a lap and wave armature winding with regards to the number of parallel paths?

Ans:- The armature winding wound on the core is given current through DC supply. This current carrying winding is under the influence of the magnetic field develops a force that develops a rotational torque. This torque enables the machine to rotate. The second role is to generate an electromotive force (E.M.F) which is proportional to the speed.

In the armature, an electro motive force is created by the relative motion of the armature & the field, when the machine or motor is used as a motor.

An armature is defined as the component of an electric machine that carries alternating current.

Following are the main parts of an armature:

- (i) Pole pieces
- (ii) Main flux
- (iii) Winding groups
- (iv) Commutator segments
- (v) Brushes
- (vi) Frame

Answer is:

- (i) Pole pieces
- (ii) Main flux
- (iii) Winding groups
- (iv) Commutator segments
- (v) Brushes
- (vi) Frame

Difference b/w Lap & Wave Winding.

LAP WINDING	WAVE WINDING
(i) The number of parallel paths in lap winding is equal to the number of poles.	The number of parallel path is always equal to two (2).
(ii) The number of carbon brushes in lap winding is equal to the number of poles.	(ii) The number of carbon brushes requirement in wave winding is 2 due to two parallel paths.
(iii) Equalizer ring is required for obtained better communication.	(iii) No need for equalizer ring.
(iv) Lap winding are used for low voltage & high current rating machines.	(iv) Wave winding is required for less high voltage but high current rating machines.
(v) Generated emf equation for simple lap winding is	(v) Generated emf equation for simple wave winding is
$E_g = \frac{P\Phi ZN}{60A}$	$E_g = \frac{P\Phi ZN}{60 \times 2} = \frac{P\Phi ZN}{120}$
(vi) The conductor current in each parallel path is (I/A) .	(vi) The conductor current in each parallel path is $(I/2)$ in wave winding.
(vii) If lap coil are traversed the movement is forward & backward alternatively.	(vii) If wave coil are traversed the movement is forward only.
(viii) The commutator pitch for lap winding is always one.	(ix) The commutator pitch for wave winding is almost equal to 2 pole pitch
(ix) It is more costly due to requirement of equalizer ring & more carbon brushes.	(x) It is comparatively cheap than lap winding.
	(xi) Wave winding is more advantageous over lap winding.

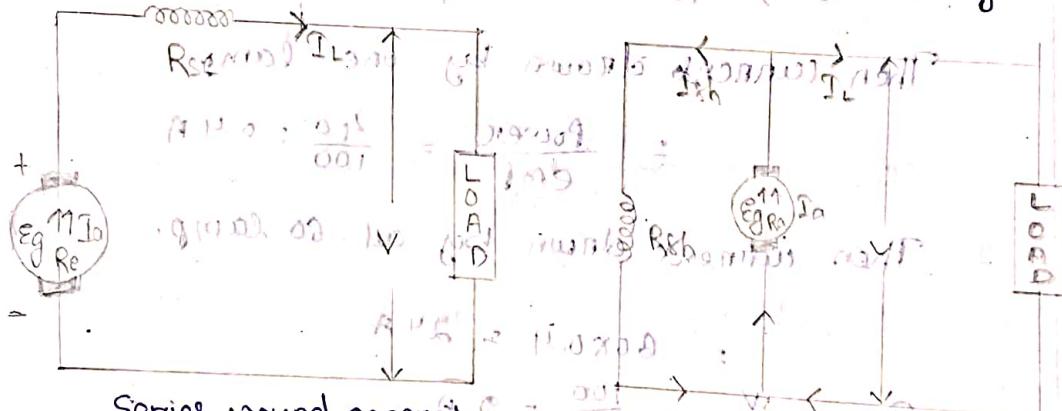
(Q) Draw the circuit diagram of the different types of self-excited DC generators in common use?

Ans:- Self excited DC generator is basically of two types :-
 1) Series wound DC generator.
 2) Shunt wound DC generator.

- 3) Compound wound DC generator.

(1) Series wound DC generator.

→ In series wound DC generator the field winding is connected in series with armature winding.



Series wound generator

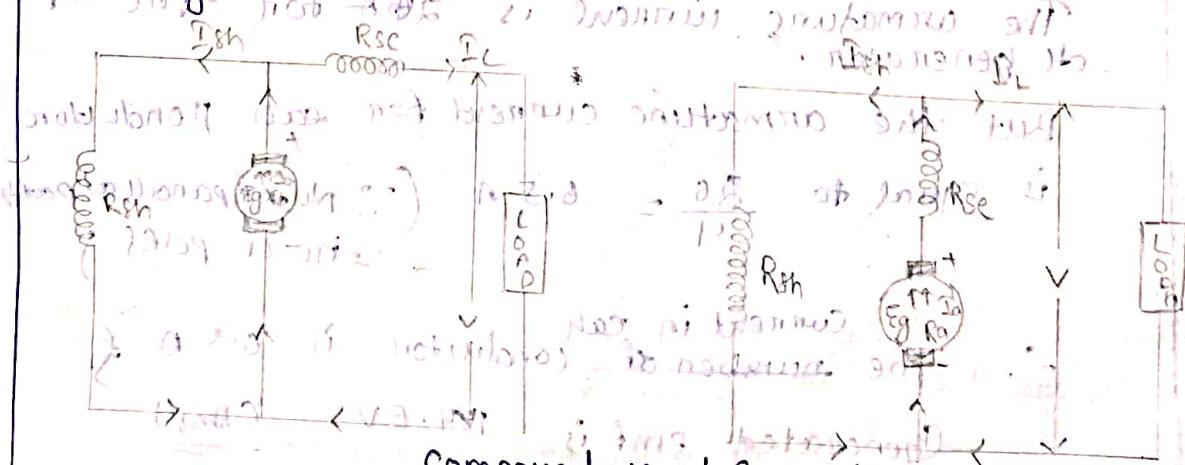
(2) Shunt wound generator:-

→ In shunt wound generator the field winding is connected in parallel with armature winding.

(3) Compound generator:-

→ In a compound generator, there are two types of field winding (one on each pole).

→ One is in series & another is in parallel with armature winding.



Compound wound generator.

(Q) Draw the circuit diagram of the different self-excited dc generators in common use?

Ans:- Self excited dc generator is basically of 3 types :-

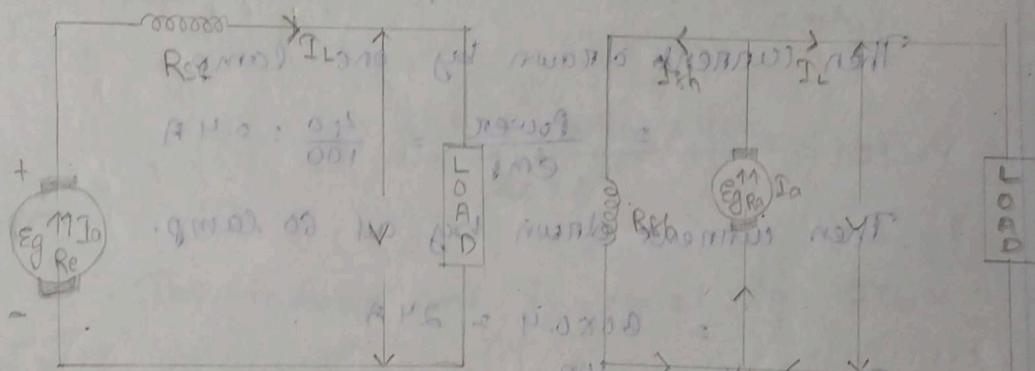
(1) Series wound dc generators

(2) Shunt wound dc generators

(3) Compound wound dc generators

(1) Series wound dc generators

→ In series wound dc generators the field winding is connected in series with armature winding.



Series wound generator Shunt wound generator

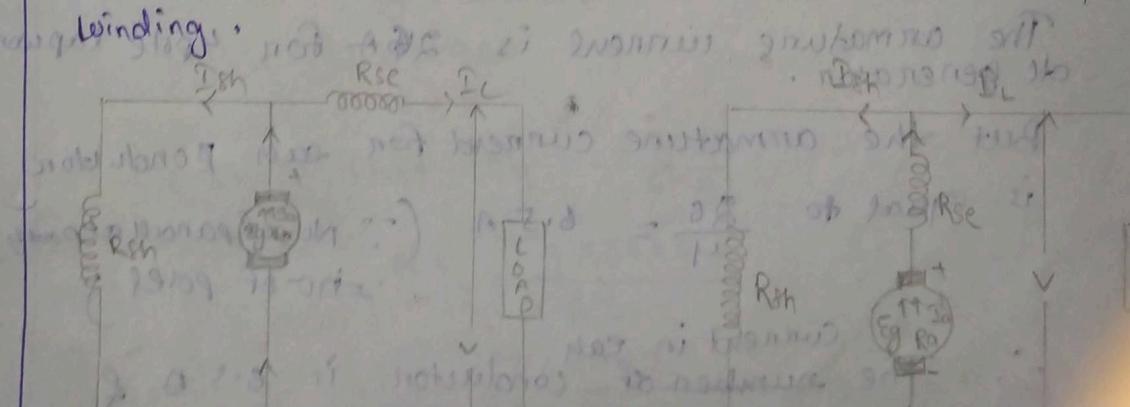
(2) Shunt wound generator:-

→ In shunt wound generator the field winding is connected in parallel with armature winding.

(3) Compound generator:-

→ In a compound generator, there are two types of field winding on each pole.

→ One is in series & another is in parallel with armature winding.



(3) A 4-pole shunt generator has a lap wound armature with resistance of 0.1Ω & field circuit resistance of 50Ω . The generator supplies 100V, 40 watt/lamp. Find the current in each armature conductor and the generated emf. The brush contact drop is 1 volt/brush?

Ans:- Given data :-

$$R_a = 0.1\Omega$$

$$R_{sh} = 50\Omega$$

$$V = 100V$$

60 lamps of 40 watt/lamp are connected in parallel.

Then current drawn by one lamp

$$= \frac{\text{Power}}{\text{emf}} = \frac{40}{100} = 0.4A$$

Then current drawn by all 60 lamp.

$$= 60 \times 0.4 = 24A$$

$$I_{sh} = \frac{V}{R_{sh}} = \frac{100}{50} = 2A$$

$$I_a = I + I_{sh} = 24 + 2 = 26A$$

The generated emf = $V + I_a R_a + \text{brush drop}$

$$= V + I_a R_a + \text{brush drop}$$

$$= 100 + (26 \times 0.1) + (2 \times 1)$$

$$= 104.6V \quad (\text{Ans})$$

The armature current is 26A for 4 pole lap wound dc generator.

But the armature current for each conductor is equal to $\frac{26}{4} = 6.5A$ (\because No. of parallel paths = no of poles)

\therefore The current in each conductor is 6.5A if

Generated emf is 104.6V. (Ans)

(4) An 8 pole lap wound dc generator has 960 conductors, a flux of 40 milliweber and is driven at 400 rpm. Find induced emf?

Ans:- Given data:

Number of poles $P = 8$ (to find pole pitch, number of slots $A = 20$)
lap wound generator.

$$Z = 960 \text{ conductors} \quad A = 20$$

$$\Phi = 40 \text{ mWb} = 40 \times 10^{-3} \text{ wb}$$

$$N = 400 \text{ rpm} \quad P = 8$$

$$A = 8$$

$$\text{Then generated emf} = E_g = \frac{P\Phi Z N}{60A^2}$$

$$= \frac{8 \times 40 \times 10^{-3} \times 960 \times 400}{60 \times 8^2} = 256 \text{ V}$$

∴ The induced emf is equal to 256 V

(5) An 8 pole wave connected dc generator has 900 armature conductors and a flux per pole of 0.04 wb. At what speed it must be driven to generate 500 v?

Ans:- Given data:

$$P = 8 \text{ poles} \quad A = 20 \text{ slots}$$

wave connected.

$$\Phi = 0.04 \text{ wb}$$

$$E_g = 500 \text{ volt}$$

$$Z = 900$$

$$N = ?$$

$$\text{we know that } E_g = \frac{P\Phi Z N}{60A}$$

$$\text{Then } N = \frac{E_g \times 60 \times A}{P\Phi Z}$$

$$= \frac{500 \times 60 \times 2}{8 \times 0.04 \times 900} = 208.3 \text{ rpm}$$

∴ The number of conductor is 208.3 rpm

(6) The armature of a 60 pole dc generator has a wave winding containing 650 conductors. calculate the Eg when flux/pole is 0.055 wb & speed is 300 rpm. Calculate the speed at which the armature must be driven to generate emf of 550 v & flux is reduced to 0.05 wb.

Ans:- $A = 2$ (wave winding)
 $P = 6$
 $Z = 650$

(i) $\Phi = 0.055$ & $N = 300$

$$E_g = \frac{P\Phi Z N}{60 \times A} = \frac{6 \times 0.055 \times 650 \times 300}{120} = 536.25 V$$

\therefore The generated emf is equal to 536.25 v.

Again

$$E_g = 550 V$$

$$\Phi = 0.05 V$$

$$P = 6$$

$$Z = 650$$

do. Now we have to find the speed. $E_g \times 60 \times A$ ~~is the product of number of poles & number of conductors~~
~~so we can write~~ Then $N = \frac{E_g \times 60 \times A}{P \Phi Z}$ ~~is the product of number of poles & number of conductors~~

$$= 338.46$$

~~339 rpm~~

\therefore The number of conductors is equal to 339.

\therefore The speed of the motor is equal to 338.46 rpm.

$$\frac{P \times Z \times N}{60 \times A} = 338.46$$

$$\frac{6 \times 650 \times N}{120 \times 2} = 338.46$$

$$N = 338.46 \times \frac{120 \times 2}{6 \times 650}$$

$$N = 109.44$$

$$N = 109$$

$$N = 109$$

$$N = 109$$

(7) An 8-pole dc generator has per pole of flux is 40 mWb & winding is connected in lap with 960 conductors. Calculate the generated emf on open circuit when it runs at 400 rpm . If the armature is wave wound at what the machine has driven to generate the same voltage?

Ans:- Given data:

$$P = 8 \quad A = 8 \quad (\text{lap wound})$$

$$\Phi = 40 \times 10^{-3} \text{ wb} \quad Z = 960 \quad N = 400 \text{ rpm}$$

$$\text{Then the generated emf} = E_g = \frac{P\Phi Z N}{60A}$$

$$= \frac{8 \times 40 \times 10^{-3} \pi \times 960 \times 400}{60 \times 8} = 256 \text{ V}$$

(ii) If wave wound then $A = 2$

$$P = 8 \\ \Phi = 40 \times 10^{-3} \text{ wb} \\ E_g = 256 \text{ V} \\ Z = 960$$

$$\text{Then } N = \frac{E_g \times 60 \times A}{P \Phi Z} = \frac{120 \times 256}{8 \times 40 \times 10^{-3} \times 960} \approx 100 \text{ rpm}$$

\therefore The required emf is 256 & speed is 100 rpm.

✓
26/4/2022

(2) function of pole shoes in dc machine?

Ans:- Naturally pole shoe is a projection over pole cone and is always in connection with pole body and fills the gap between the yoke & the pole body.

functions of pole shoe:-

- It supports the field coil.
- It spreads out the magnetic flux in the air gap.
- It reduces the reluctance of the magnetic path.

A combination of pole body and pole shoe is termed as field magnet. This behaves as a field magnet when direct current is passed through the field coil.

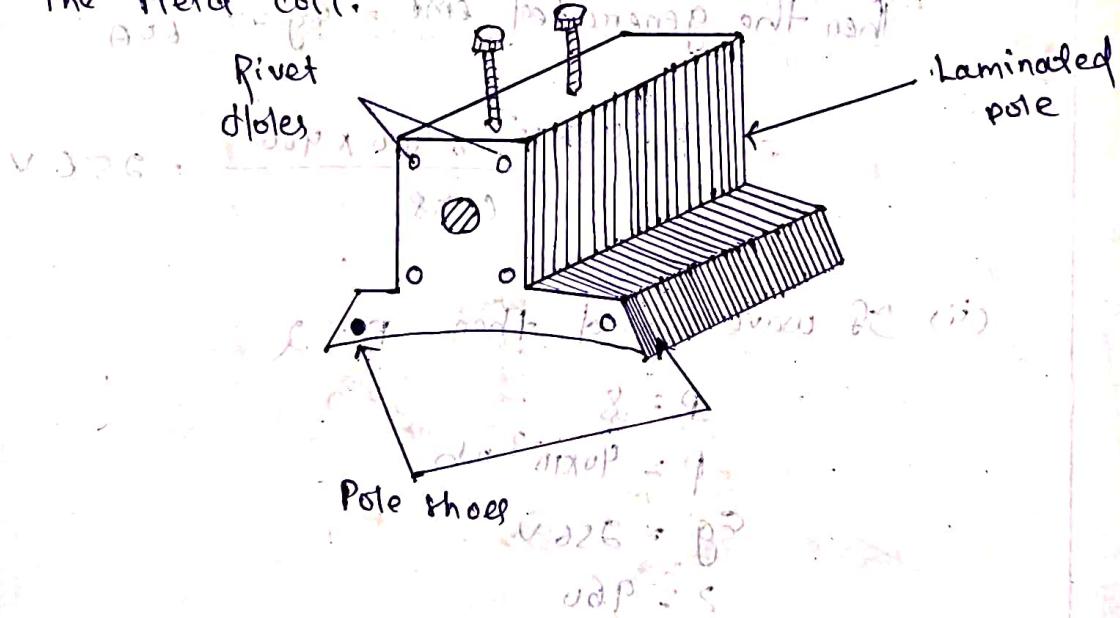


Diagram of a DC motor pole:

1. Pole shoe →

2. Pole body →

3. Laminated pole →

Pole shoe of DC motor has following parts:

1. Main pole →

2. Pole shoe →

(3) State the working principle of dc motor?

Ans:- A dc motor is defined as a class of electrical motors that convert direct current electrical energy (from battery) into mechanical energy, to provide motion.

Working Principle:-

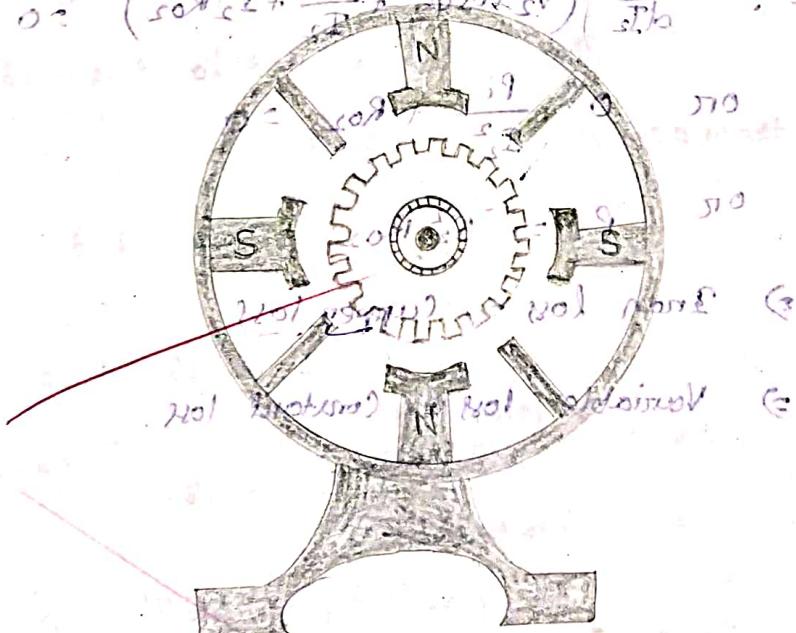
When kept in a magnetic field; a current carrying conductor gains torque and developed tendency to move. In short, when electric field and magnetic fields interact; a mechanical force arises. This is the principle on which the dc motor works.

(William Sturgeon invented the first dc motor in 1886.)

What is principle of motor?

(torque \propto $I \times B$) $\theta = (magnetic)$

$$\theta = (constant + \frac{I}{R} \cdot m)$$



Not balanced

Not balanced due to unbalanced magnetic field

Not balanced due to unbalanced magnetic field

(4) What are the maximum conditions for maximum efficiency in the secondary of system 2 if A = 100?

~~Ans: Maximum torque occurs with constant loadings.~~

Efficiency of autotransformer (full load)

\rightarrow ignoring primary losses

loading $\alpha = \frac{\text{full load VA} \times \text{PF}}{\text{no-load loss}}$

losses $= (\text{full load VA}) \times \text{PF} + P_i + P_c$

losses $= V_2 I_2 \cos \phi_2$ (no-load losses)

losses $= V_2 I_2 \cos \phi_2 + P_i + I_2^2 R_{02}$ (iron loss)

losses $= V_2 I_2 \cos \phi_2 + P_i + I_2^2 R_{02}$ (iron loss)

losses $= V_2 I_2 \cos \phi_2 + \frac{P_i}{R_2} + I_2^2 R_{02}$ (iron loss)

Condition for maximum efficiency is that

$$\frac{d}{dI_2} \left(\text{denominator} \right) = 0 \quad (V_2 \rightarrow \text{constant}).$$

$$\therefore \frac{d}{dI_2} \left(V_2 \cos \phi_2 + \frac{P_i}{I_2} + I_2^2 R_{02} \right) = 0$$

$$\text{or } 0 - \frac{P_i}{I_2^2} + R_{02} = 0$$

$$\text{or } P_2 = I_2^2 R_{02}$$

\Rightarrow Iron loss = Copper loss

\Rightarrow Variable loss = Constant loss.

(1) A dc shunt generator has full load current of 196A at 220V. The stray losses are 720Watt & the shunt field resistance is 55Ω. If it has a full load efficiency of 88%, find the armature resistance and also find the load current corresponding to maximum efficiency?

Ans:-

Given data:-

$$I_{FL} = 196A$$

$$V_L = 220V$$

$$\text{Stray loss} = 720 \text{ watt}$$

$$R_{sh} = 55\Omega$$

$$(\eta) \text{ efficiency} = 88\% = 0.88$$

Now, $R_a = ?$ To solve this, we will use the following diagram:

$$I_{sh} = \frac{V_L}{R_{sh}} = \frac{220}{55} = 4A$$

$$I_{av} = I_{sh} + I_L = 196 + 4 = 200A$$

Output of the generator $V_L I_L$

$$= 220 \times 196 = 43120 \text{ watt}$$

$$\text{Efficiency} = \eta = \frac{\text{Output}}{\text{Input}}$$

$$0.88 = \frac{43120}{\text{Input}}$$

$$0.88 = \frac{43120}{\text{Output} + \text{losses}}$$

$$0.88 = \frac{43120}{\text{Output} + \text{losses}} = 0.88 \times \text{Output}$$

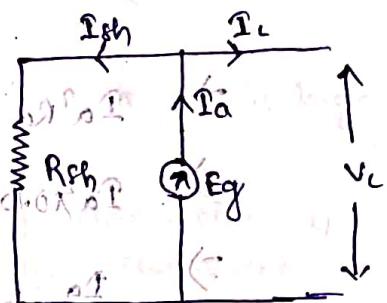
$$\text{Losses} = \left(\frac{43120}{0.88} \right) - 43120$$

$$\text{Losses} = 5880 \text{ watt}$$

We know total loss = Stray loss + $I_a^2 R_a + I_{sh}^2 R_{sh}$

$$5880 = 720 + 40000 \times (200)^2 \times R_a + (4^2 \times 55)$$

$$5880 = 1600 + 40000 \times R_a$$



$$\text{Total current } I_a = \frac{5880 - 1600}{40000} = 0.107 \text{ A}$$

Hence armature current $I_a = 0.107 \text{ A}$

$$I_a^2 R_a = 0.107^2 \times 0.107 = 0.0011 \text{ W}$$

Minimum torque required to start the motor $T_m = 0.0011 \text{ Nm}$

Conditions for maximum efficiency

Constant loss \rightarrow Variable loss \rightarrow Minimum efficiency

$$I_a^2 R_a = I_{sh}^2 R_{sh} + 720$$

$$I_a^2 \times 0.107 = 880 + 720$$

$$I_a = \sqrt{\frac{1600}{0.107}} = 122.28 \text{ A}$$

$$\therefore I_a = 122.28 \text{ A}$$

(5) Write the voltage equation of a dc motor?

Ans:- The voltage applied across the motor armature has to

- (i) Overcome the back electromotive force and
- (ii) Supply the armature ohmic drop separately

$$V = E_b I_a + I_a^2 R_a$$

$$V = E_b I_a + I_a^2 R_a$$

This is known as voltage equation of a motor.

By multiplying I_a in both sides we get

$$V I_a = E_b I_a + I_a^2 R_a$$

Where $V I_a$ = Electrical input to armature

~~$E_b I_a$ = Electrical equivalent of mechanical power developed in the armature~~

~~$I_a^2 R_a$ = Cess. loss in armature~~

~~$E_b I_a + I_a^2 R_a = 200 \text{ W}$~~

$$(220 \text{ V})^2 / 0.107 \times (0.107)^2 + 0.107^2 \times 0.107 = 0.882$$

$$0.0004 + 0.001 = 0.882$$

(6) Explain about different characteristics of ~~old~~ (3)
series motor?

- Ans:- The outstanding characteristics of a series motor is:-
- (i) It has high torque at low speeds and vice-versa.
 - (ii) It is well suited for traction purpose such as electric trains.
 - (iii) Acceleration is rapid because the torque is high at low speeds.
 - (iv) The series motor automatically slow down as the train goes up an incline surface, yet turns at top speed on the flat ground.
 - (v) The power of a series motor tends to be constant.
 - (vi) Because high torque is accompanied by low speed of vice-versa.
 - (vii) Series motors are also used in electric arcans.
 - (viii) Light loads are lifted quickly & heavy loads are more slowly.

(7) Applications of Compound Motor?

Ans:- The main applications of a compound motor are

- for intermittent & high torque loads.
- for shears and puncher.
- elevators.
- conveyor.
- Heavy plannent.
- Rolling mills.
- Ice machines.
- Printing press.
- AC (Air compression).

(final part)

(8) Derive the torque eqn developed in the shaft of armature?

Ans:- Armature torque of a motor:-
Armature torque of a motor is due to the force exerted by the magnetic field on the conductors carrying current.

Let torque developed = T_a Nm

Speed = N rpm.

Then power developed = $T_a \times 2\pi N$ watt

We also know that electric power converted into mechanical power in the armature.

Electric power = $E_b I_a$ watt

we get $T_a \times 2\pi N = E_b I_a$

we know $E_b = \frac{P\Phi^2 N}{60A}$

we get $T_a \times 2\pi N = \frac{P\Phi^2 N}{60A} \times I_a$

$$T_a \times 2\pi N = \frac{P\Phi^2 N}{60A} \times I_a$$

$$T_a = \frac{1}{2\pi} \times \frac{P\Phi^2}{60A} \times I_a$$

$$\Rightarrow T_a = \frac{1}{120\pi} \times \frac{P\Phi^2}{60A} \times I_a$$

$$T_a = \frac{1}{120\pi} \times \frac{P\Phi^2}{60A} \times I_a$$

Shaft torque of a motor:-

T_{sh} = shaft torque

$$T_{sh} = \frac{\text{Output in watts}}{2\pi N / 60}$$

$$= \frac{60 \text{ Output}}{2\pi N}$$

Note:- $T_a - T_{sh}$ = lost torque (due to iron friction losses)

(1) Emf equation of a transformer?

Ans:- Let N_1 = No of turns in primary coil.

N_2 = No of turns in secondary coil.

Φ_m = Maximum flux in core in weber.
 $= B_m A$

frequency of ac input (Hz)

$$\Phi_m = \Phi_m \sin \omega t$$

The instantaneous emf (e_1) induced in the primary

$$e_1 = -N_1 \frac{d\Phi}{dt} = -N_1 \frac{d}{dt} (\Phi_m \sin \omega t)$$

$$= -N_1 \Phi_m \cos \omega t = -2\pi f N_1 \Phi_m \cos \omega t$$

$$= 2\pi f N_1 \Phi_m \sin (\omega t - 90^\circ)$$

It is clear from the above eqn. that maximum value of induced emf in the primary is

$$E_{m1} = 2\pi f N_1 \Phi_m$$

The rms value of E_1 of the primary emf is

$$E_1 = \frac{E_{m1}}{\sqrt{2}} = \frac{2\pi f N_1 \Phi_m}{\sqrt{2}} = 4.44 f N_1 \Phi_m$$

Similarly, the $- \frac{d\Phi}{dt}$ in the secondary coil is

$$e = -N_2 \frac{d\Phi}{dt}$$

$$\text{or } e = -N \frac{d\Phi}{dt}$$

$$\therefore E_2 = 4.44 f \Phi_m N_2$$

The required eqn of transformer.

(Ans)

21/20/12 - 7:20 AM

Assignment 1-24

Q.1 Explain Practical transformer on load & draw the phasor diagram?

Ans:- Practical transformer on load :-

(i) Problem :-

Two cases : (i) When such a transformer is assumed to have no winding resistance and leakage flux.

(ii) When the transformer has winding resistance and leakage flux.

(i) No winding resistance & leakage flux :-

Practical transformer with the assumption that resistance & leakage reactances of the windings are negligible.

$$\frac{\Phi_b}{I_b} n_1 = \frac{\Phi_b}{I_b} n_2 = 1$$

Assumption, $V_2 = E_2$ & $V_1 = E_1$

Let us take the usual case of inductive load which causes (the 2^o) current I_2 to keep the 2^o voltage V_2 by ϕ_2 .

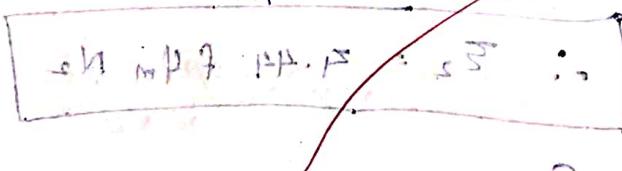
The total current I_2 must meet two requirements.

(a) It must supply the no load current to meet the iron losses in the transformer & to provide flux in the core.

(b) It must supply a current I_2 to counter the demagnetizing effect of 2^o current. The magnitude of I_2 will be such that

$$N_1 I_2 = N_2 I_2$$

$$R_2 = \left[\frac{\Phi_b}{N_2 I_2} \right] = K I_2$$



nonzero work to be done per cycle

(Ans)

Phasor diagram:- Φ_1 & E_2 → Lag behind the mutual flux Φ by 90°

I_1 & I_2 → 90° lagging current ahead of Φ by 90°

$I_2 = kI_1$ & it is antiphase with Φ

$E_2, I_2 \Rightarrow$ no load current of the transformer.

→ The value 'k' is assumed to be < 1 .

Unity load condition probability \Rightarrow

so that

1° phasor $\delta = 2^\circ$ phasor

1° power factor $= \cos \phi_1$

2° power factor $= \cos \phi_2$

1° input power $= V_1 I_1 \cos \phi_1$

2° output power $= V_2 I_2 \cos \phi_2$

Q:2 What is equivalent reactance?

Ans: When secondary resistance or reactance is transferred to the primary, it is divided by k^2 . It is then called equivalent secondary reactance.

It is denoted by R_2' or x_2'

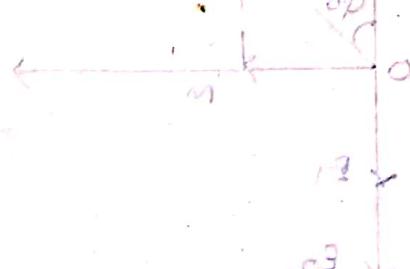
(3) What is step up & stepdown transformer?

Ans: - (i) Step up transformer: In this transformer the input voltage is increased. Here input voltage is less than output voltage ratio > 1

(ii) Step down transformer: - Here the input voltage is decreased. Here input voltage is more than output voltage.

$V_o > V_i$ \therefore $k > 1$

$V_o < V_i$ \therefore $k < 1$



(4) Define voltage regulation:-

Ans:- It is the arithmetic difference between no-load secondary voltage & the primary voltage on load expressed as % of no-load voltage.

$$\rightarrow \text{Voltage regulation} = \frac{\Delta V_2 / V_2 \times 100}{V_2}$$

Where $\Delta V_2 \rightarrow$ no-load secondary voltage
 $V_2 \rightarrow$ secondary voltage on load

(5) What are the losses of transmission transformer?

Ans:- The losses occur in a transformer :-

\rightarrow Copper loss \rightarrow Hysteresis loss

\rightarrow Copper losses \rightarrow I^2 of the resistance of the winding

(6) Explain variable losses; -

Ans:- When the transformer is loaded current flows

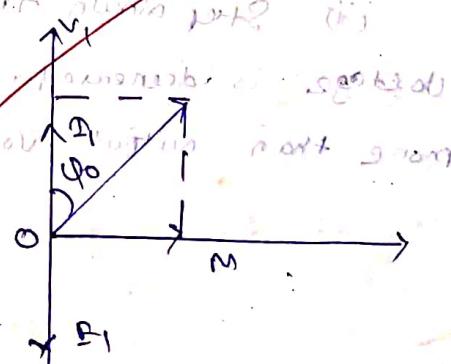
in primary & secondary winding, there is loss of electrical energy due to the resistance of the primary winding & secondary winding & they are called

variable losses.

\rightarrow In a transformer copper losses are variable.

(7) Draw the phasor diagram of practical transformer in load condition.

Ans:-



(8) Derive voltage transformation ratio?

Ans:-

$$\text{Induced emf} = \frac{E_2}{N_1} = \frac{V_2}{N_1} = K$$

→ Here the constant 'K' is called as voltage transformation ratio.

→ for an ideal transformer.

$$K = \left[\text{If } N_2/N_1 = n \text{ then } E_2 = n E_1 \right]$$

(9) Derive the h.c.f. equation of transformer?

Ans:- If $\Phi_m \sin \omega t$ is the flux passing per pi.

induced emf in primary winding is

$$e_1 = -N_1 \frac{d\Phi}{dt} = -N_1 \frac{d}{dt} (\Phi_m \sin \omega t)$$

$$= -2\pi f N_1 \Phi_m \cos \omega t = -2\pi f N_1 \Phi_m \cos \omega t$$

$$= 2\pi f N_1 \Phi_m \sin (\omega t + 90^\circ) \quad \text{.....(1)}$$

The maximum value of $\sin(\omega t + 90^\circ) = 1$

⇒ maximum induced emf in primary winding

$$e_{m1} = 2\pi f N_1 \Phi_m$$

The rms value of induced emf in primary winding

~~$$e_1 = \frac{e_{m1}}{\sqrt{2}} = \frac{2\pi f N_1 \Phi_m}{\sqrt{2}}$$~~

Similarly

$$e_2 = 4.44 f N_2 \Phi_m$$

$$e_1 = 4.44 f N_1 \Phi_m$$

∴ $e_2/e_1 = N_2/N_1$ or $N_2/N_1 = e_2/e_1$

∴ $(4.44 f N_2 \Phi_m) / (4.44 f N_1 \Phi_m)$

$$\therefore (N_2 \Phi_m) / (N_1 \Phi_m) = \frac{e_2}{e_1}$$

$$\therefore N_2 / N_1 = e_2 / e_1$$

∴ $e_2 / e_1 = N_2 / N_1$

(10) What is ideal transformer?

Ans:- An ideal transformer has no loss.

→ No winding resistance with respect to primary.

→ No leakage flux, iron saturation is absent.

→ No iron losses, ratio is not constant.

(11) What is the working principle of transformer?

Ans:- When an alternating voltage V_1 is applied

in the primary side, an alternating flux Φ is set up in the core.

→ This alternating flux links both windings & induced emfs E_1 & E_2 in them according to

Faraday's law of electromagnetic induction.

(12) Derive the condition for maximum efficiency?

Ans:- Opt. power $\Rightarrow V_2 I_2 \cos \phi_2$

If R_{02} is the total resistance of the transformer referred to secondary side.

$$\text{Total CW loss} = P_c = I_2^2 R_{02}$$

~~$$\text{Transformer efficiency } \eta = \frac{V_2 I_2 \cos \phi_2}{V_2 I_2 \cos \phi_2 + P_c + I_2^2 R_{02}}$$~~

~~$$\text{Total loss} = P_c \text{ (constant)}$$~~

~~$$\text{for normal transformer } V_2 = \text{constant}$$~~

→ For a load of given P.F. efficiency depends upon a load current

$$\frac{d}{d I_2} (V_2 \cos \phi_2 + P_c + I_2^2 R_{02}) = 0$$

$$\therefore P_c = I_2^2 R_{02}$$

∴ Non loss = copper loss

Assignment:- 4

- ① What is impedance ratio?
- Ans:- Impedance matching audio transformers always give their impedance ratio value from one winding to another by the square of the their turns ratio. That is their impedance ratio is equal to its turns ratio squared and also its primary to secondary voltage ratio squared as shown.

$$\frac{Z_2}{Z_1} = \left(\frac{N_2}{N_1}\right)^2 = k^2$$

Let Z_2 = Secondary impedance of a transformer

$$\Rightarrow Z_2 = \frac{V_2}{I_2}$$

$$\Rightarrow Z_1 = \frac{V_1}{I_1}$$

$$\Rightarrow \frac{Z_2}{Z_1} = \frac{V_2}{I_2} \times \frac{\frac{I_1}{V_1}}{\frac{I_2}{V_2}} = \frac{V_2}{I_2} \times \frac{I_1}{V_1}$$

$$\Rightarrow \frac{Z_2}{Z_1} = \frac{V_2}{V_1} \times \frac{I_1}{I_2} = k^2$$

Similarly $\frac{R_2}{R_1} = k^2$, $\frac{x_2}{x_1} = k^2$

- (2) Explain about setting of x_L , R & z with respect to primary side?

Ans:- When secondary quantities are referred to primary resistance/reactances are divided by k^2 . Voltage are divided by k & currents are multiplied by k .

~~Actual Secondary voltage $V_2' = k V_2$~~

~~Actual Secondary current $I_2' = I_2 / k$~~

$$I_2' = k I_2$$

$$R_2' = \frac{R_2}{k^2} \quad \& \quad x_{2'} = \frac{x_2}{k^2}$$

$$V_2' = \frac{V_2}{k}$$

$$Z_2' = \frac{Z_2}{k^2}$$

P.T. Transformer

(3) Draw the equivalent circuit of ideal transformer with primary to primary side?

~~Ans:- The equivalent circuit diagram of an ideal transformer is a simplified circuit diagram in which the impedance, resistance, leakage reactance of transformer can be more easily calculated.~~

$$I_2 = I_2' k$$

$$Z_2' = k^2 Z_2$$

$$\Rightarrow Z_2 = \frac{Z_2'}{k^2}$$

$$\frac{R_2}{k^2}$$

$$R_2 = \frac{R_2'}{k^2}$$

$$\frac{R_2'}{k^2} = \frac{R_2}{k^2} = \frac{R_2}{k^2}$$

$$= \frac{10 \times 10}{100} = \frac{100}{100} = 1 \Omega$$

$$X_2' = \frac{X_2}{k^2} = \frac{X_2}{100} = \frac{10}{100} = 0.1 \Omega$$

Equivalent circuit diagram of primary side

Primary winding of 20 turns is connected to 10V DC source

Primary side voltage and current relationship is given by $\frac{V_1}{V_2} = \frac{N_1}{N_2}$ and $I_1 = k I_2$

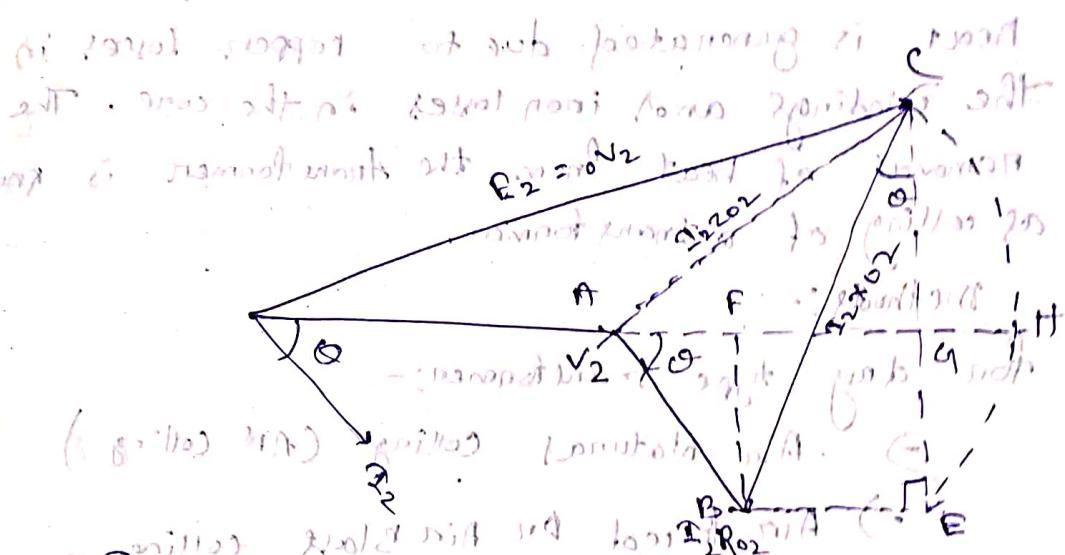
Secondary side voltage and current relationship is given by $\frac{V_2}{V_1} = \frac{N_2}{N_1}$ and $I_2 = k I_1$

Primary side voltage and current relationship is given by $\frac{V_1}{V_2} = \frac{N_1}{N_2}$ and $I_1 = k I_2$

Secondary side voltage and current relationship is given by $\frac{V_2}{V_1} = \frac{N_2}{N_1}$ and $I_2 = k I_1$

(4) Explain about the exact voltage drop with phasor diagram?

Ans: In a power system, the voltage drop is measured at the load point from primary side.



During no-load condition, induced voltage at the primary and secondary winding and the primary one is equal to the applied voltage of secondary terminal voltage respectively. If ωN_2 be the secondary terminal voltage, then we can write $E_2 = \omega N_2$. Let V_2 be the secondary voltage on load.

$$\text{Hence } V_2 = A F f F G = A F f B E$$

$$= I_2 R_{02} \cos \theta + I_2 X_{02} \sin \theta - \text{eqn-A}$$

The approximate voltage drop shown in eqn-A for lagging power factor only.

For leading pf the approximate voltage drop will be

$$= I_2 R_{02} \cos \theta - I_2 X_{02} \sin \theta. \quad \text{eqn-B}$$

% Voltage drop in secondary is

$$\frac{I_2 R_{02} \cos \theta \pm I_2 X_{02} \sin \theta}{V_2} \times 100$$

$$= \frac{V_1 \cos \theta \pm V_1 \sin \theta}{V_2} \times 100$$

(5) To explain about the cooling method of transformer? (12)

Ans:- When a transformer is in operation, heat is generated due to copper losses in the windings and iron losses in the core. The removal of heat from the transformer is known as cooling of transformer.

Methods:-

For dry type transformer:-

→ Air Natural Cooling (ANL cooling)

→ Air forced or Air Blast cooling

For oil immersed type transformer

→ Oil Natural Air Natural (OIN) cooling

→ Oil Natural Air forced (ONAF) cooling

→ Oil forced Air forced (OFAB) cooling

→ Oil forced Water forced (OFWF) cooling

$$A = P \rho \rightarrow A = \pi r^2 d \times L + \pi D^2 \times L$$

$$A = P \rho \rightarrow \pi r^2 d \times L + \pi D^2 \times L$$

∴ Amount of air required = $\frac{P}{\rho}$

∴ If no natural cooling is there then $A = \infty$

∴ Actual cooling area $= A - \text{critical area}$

∴ This area

$$A = P \rho \rightarrow \text{critical } A = 2 \times \text{cooling } L$$

∴ Probable air gap option

$$0.01 \times \text{cooling } L + \text{allow loss } L$$