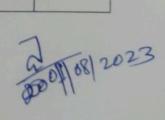
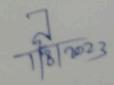
DISCIPLINE - ELECTRICAL ENGG	SEMESTER 5TH	NAME OF THE TEACHING FACULTY- JYOTIRMAY LECT(ELECT.)	EE SETHY,
SUB- EC-II	NO OF DAYS PER WEEK CLASS ALLOTED- 4 CLASS DAY	SEMESTER FROM 01.08.2023 TO 30.11.2023 NO OF WEEK – 15WEEKS	
WEEK		THEORY	
1 ST WEEK	1 ST day 2 nd day 3 rd day 4 th day	ALTERNATOR: Types of alternator and their constructionalfeatures. Basic working principle of alternator and the relation between speed and frequency. Terminology in armature winding and expressions for winding factors (Pitch factor, Distributionfactor).	STATUS
2 ND WEEK	1 ST day 2 nd day 3 rd day 4 th day	 1.4. Explain harmonics, its causes and impact on windingfactor. 1.5. E.M.F equation of alternator. (Solve numericalproblems). 1.6. Explain Armature reaction and its effect on emf at different power factor of load. 1.7. The vector diagram of loaded alternator. (Solve numericalproblems) 	
3 RD WEEK	1 st day 2 nd day 3 rd day 4 th day	Testing of alternator (Solve numerical problems) 1.8.1. Open circuittest. 1.8.2. Short circuittest. Determination of voltage regulation of Alternator by direct loading and synchronous impedance method. (Solve numericalproblems)	
4 TH WEEK	1 ST day 2 nd day 3 rd day 4 th day	1.10. Parallel operation of alternator using synchro-scope and dark & bright lamp method. 1.11. Explain distribution of load by parallel connectedalternators.	
TH WEEK	1 ST day 2 nd day 3 rd day 4 th day	2. SYNCHRONOUSMOTOR: 2.1. Constructional feature of SynchronousMotor. 2.2. Principles of operation, concept of loadangle 2.3. Derive torque, powerdeveloped.	



6 TH WEEK	1 ST day 2 nd day 3 rd day 4 th day	 2.4. Effect of varying load with constantexcitation. 2.5. Effect of varying excitation with constantload. 2.6. Power angle characteristics of cylindrical rotormotor. 2.7. Explain effect of excitation on Armature current and powerfactor. 2.8. Hunting in SynchronousMotor. 2.9. Function of Damper Bars in synchronous motor andgenerator. 2.10. Describe method of starting of Synchronousmotor. 2.11. State application of synchronous motor.
7 [™] WEEK	1 ST day 2 nd day 3 rd day 4 th day	3. THREE PHASE INDUCTIONMOTOR: 3.1. Production of rotating magneticfield. 3.2. Constructional feature of Squirrel cage and Slip ring inductionmotors. 3.3. Working principles of operation of 3-phase Induction motor. 3.4. Define slip speed, slip and establish the relation of slip with rotorquantities. 3.5. Derive expression for torque during starting and running conditions and derive conditions for maximum torque. (solve numericalproblems)
8 TH WEEK	1 ST day 2 nd day 3 rd day 4 th day	3.6. Torque-slipcharacteristics. 3.7. Derive relation between full load torque and starting torque etc. (solve numericalproblems) 3.8. Establish the relations between Rotor Copper loss, Rotor output and Gross Torque and relationship of slip with rotor copper loss. (solve numerical problems) 3.9. Methods of starting and different types of starters used for three phase Inductionmotor.
9 TH WEEK	1 ST day 2 nd day 3 rd day 4 th day	3.10. Explain speed control by Voltage Control, Rotor resistance control, Pole changing, frequency controlmethods. 3.11. Plugging as applicable to three phase inductionmotor. 3.12. Describe different types of motorenclosures. 3.13. Explain principle of Induction Generator and state itsapplications.

1/8/2023

10 [™] WEEK	1 ST day 2 nd day 3 nd day 4 th day	4. SINGLE PHASE INDUCTIONMOTOR: 4.1. Explain Ferrari'sprinciple. 4.2. Explain double revolving field theory and Cross-field theory to analyze starting torque of 1-phase inductionmotor. 4.3. Explain Working principle, Torque speed characteristics, performance characteristics and application of following single phasemotors. 4.3.1. Split phasemotor.	
11 [™] WEEK	1 ST day 2 nd day 3 rd day 4 th day	4.3.2. Capacitor Startmotor. 4.3.3. Capacitor start, capacitor runmotor. 4.3.4. Permanent capacitor type motor. 4.3.5. Shaded polemotor. 4.4. Explain the method to change the direction of rotation of abovemotors.	
12 [™] WEEK	1 ST day 2 nd day 3 rd day 4 th day	5. COMMUTATORMOTORS: 5.1. Construction, working principle, running characteristic and application of single phase seriesmotor. 5.2. Construction, working principle and application of Universalmotors.	
13TH WEEK	1 ST day 2 nd day 3 rd day 4 th day	 5.3. Working principle of Repulsion start Motor, Repulsion start Induction run motor, Repulsion Inductionmotor 6. SPECIAL ELECTRICALMACHINE: 6.1. Principle of Steppermotor. 6.2. Classification of Steppermotor. 6.3. Principle of variable reluctant stepper motor. 	
14 TH WEEK	1 ST day 2 nd day 3 rd day 4 th day	6.4. Principle of Permanent magnet steppermotor. 6.5.Principle of hybrid steppermotor. 6.6.Applications of Stepper motor. 7. THREE PHASE TRANSFORMERS: 7.1.Explain Grouping of winding, Advantages.	



15 TH WEEK	1 ST day 2 nd day 3 rd day 4 th day	7.1. Explain parallel operation of the three phasetransformers. 7.2. Explain tap changer (On/Off load tapchanging) 7.3. Maintenance Schedule of PowerTransformers.
3. 725		

1/8/2023